

1. As shown in figure 1, a vertical load  $W$  is applied to the linkage at  $B$ . The constant of the spring is  $k$ , and the spring is unstretched when  $AB$  and  $BC$  are horizontal. Neglecting the weight of the linkage, **use principle of virtual work** to derive an equation in  $\theta$ ,  $W$ ,  $l$ , and  $k$  that must be satisfied when the linkage is in equilibrium. If you use methods other than the *principle of virtual work*, only maximum up to 10 points will be given. (20%)

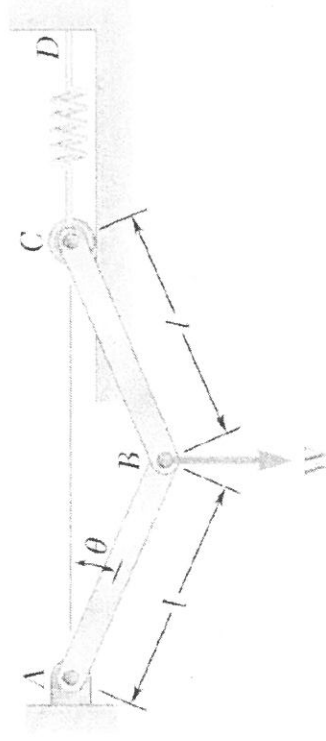


Figure 1

2. For the frame and loading shown in figure 2, determine the x- and y-components of all forces acting on member  $ABE$ . (20%)

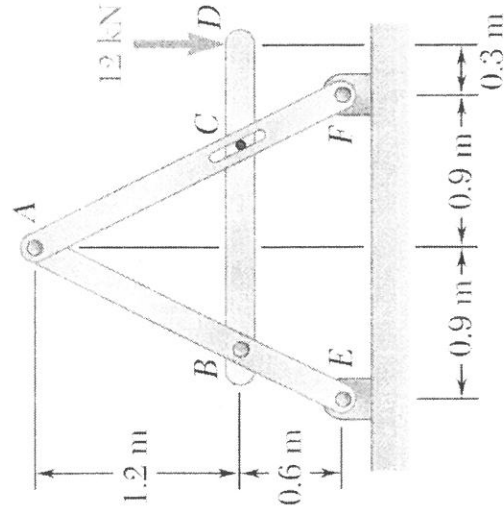
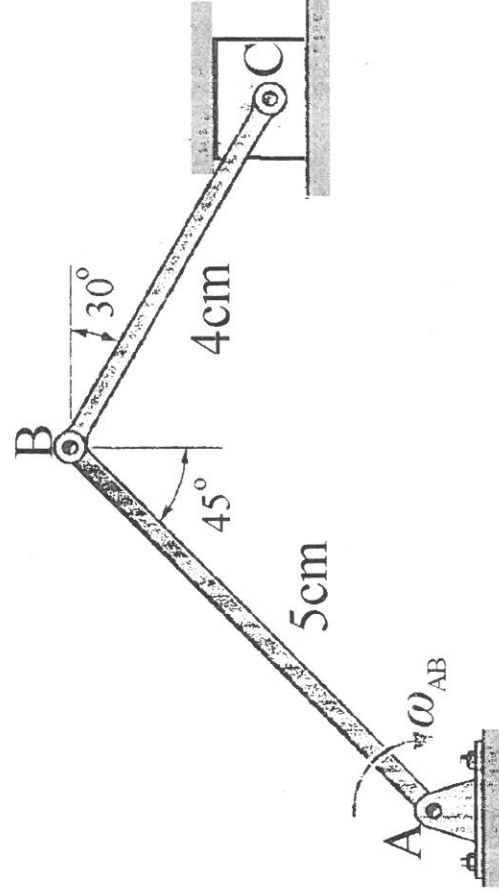
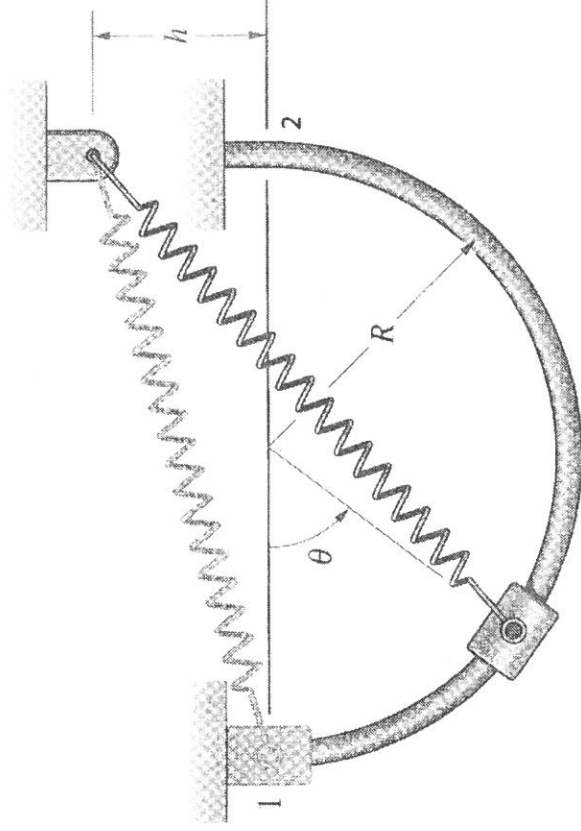


Figure 2

3. Determine the angular velocity of link  $AB$  at the instant shown if block  $C$  is moving right-ward at 12cm/s. (20%)



4. In the mechanical delay switch shown in Figure, and electromagnet releases the 1 kg slider at position 1. Under the actions of gravity and the linear spring, the slider moves along the smooth bar from position 1 to position 2, closing the switch. The constant of the spring is  $k = 40\text{N/m}$ , and its unstretched length is  $r_0 = 50\text{ mm}$ . The dimensions are  $R = 200\text{ mm}$  and  $h = 100\text{ mm}$ . Please determine the velocity of the slider's when the  $\theta = 60\text{ deg}$ . (20%)



5. The slender bar of length  $l$  and mass  $m$  is pinned to the vertical shaft at O. The vertical shaft rotates with a constant angular velocity  $\omega_0$ . Please find the value of necessary for the bar to remain at a constant angle  $\beta$  relative to the vertical. (20%)

